

Ex : $\underline{A} = \begin{bmatrix} -11 & 0 & -4 \\ -1 & -9 & -1 \\ 1 & 0 & 1 \end{bmatrix}$, $|\underline{A} - \lambda \underline{I}| = 0 \Rightarrow \dots$
 $\dots \Rightarrow \lambda = -9, -9, -9$

Solve $(\underline{A} - (-9)\underline{I}) \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ (algebraic multiplicity 3)
 $\begin{bmatrix} -2 & 0 & -4 \\ -1 & 0 & -1 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

augmented matrix

$$\left[\begin{array}{ccc|c} -2 & 0 & -4 & 0 \\ -1 & 0 & -1 & 0 \\ 1 & 0 & 2 & 0 \end{array} \right]$$

$R_1 \xleftrightarrow{\text{swap}} R_2$ $\left[\begin{array}{ccc|c} -1 & 0 & -1 & 0 \\ -2 & 0 & -4 & 0 \\ 1 & 0 & 2 & 0 \end{array} \right]$

$R_1 \rightarrow (-1)R_1$
 $R_2 \rightarrow R_2 + 2R_1$ $\left\{ \begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 2 & 0 \end{array} \right\}$

$R_2 \xleftrightarrow{\text{swap}} R_3$ $\left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$

$R_2 \rightarrow R_2 - R_1$ $\left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$

b free, a, c leading $\begin{cases} a + c = 0 \\ c = 0 \end{cases} \Rightarrow a = 0$

so solutions for $(\underline{A} - (-9)\underline{I}) \begin{bmatrix} a \\ b \\ c \end{bmatrix} = 0$ are

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ b \\ 0 \end{bmatrix} = b \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

only one basis vector, pick $b=1$, $\underline{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$.

Because $\lambda = -9$ has alg. mult. 3, but we found one lin. indep eigenvector (the \underline{v}_1 we just found),

$\dim(\mathcal{E}_{-9}) = 1 \Rightarrow$ geom-mult. 1, and so $\lambda = -9$ has defect $d = 3 - 1 = 2$. So we need to find 2 generalized e-vects $\underline{v}_2, \underline{v}_3$

Use (method 2) to make a "chain" of length

3, namely just want $\underline{v}_1, \underline{v}_2, \underline{v}_3 \neq 0$ such

$$\text{that } \begin{cases} (\underline{A} - \lambda \underline{I})^3 \underline{v}_3 = 0 \\ \underline{v}_2 := (\underline{A} - \lambda \underline{I}) \underline{v}_3 \quad (\text{needs to be } \neq 0) \\ \underline{v}_1 := (\underline{A} - \lambda \underline{I}) \underline{v}_2 \quad (\quad " \quad " \quad " \quad) \end{cases}$$

Using \underline{A} from example and $\lambda = -9$, we find that

$$\begin{aligned} (\underline{A} - (-9)\underline{I})^3 \begin{bmatrix} a \\ b \\ c \end{bmatrix} &= 0 \\ \Rightarrow \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} &= 0 \end{aligned}$$

so a, b, c free. Pick $a=1, b=0, c=0$,
 $\underline{v}_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. Then

$$\begin{aligned} \underline{v}_2 &= (\underline{A} - (-9)\underline{I}) \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -2 & 0 & -4 \\ -1 & 0 & -1 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} (\neq 0) \end{aligned}$$

$$\begin{aligned} \underline{v}_1 &= (\underline{A} - (-9)\underline{I}) \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} \\ &= \dots = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \end{aligned}$$

(which happens to be the same \underline{v}_1 we found earlier, but it isn't always like this)

What if we picked $a=0$, $b=1$, $c=0$ and made $\underline{v}_3 := \begin{bmatrix} 0 \\ 0 \end{bmatrix}$?

$$\begin{aligned}\text{Then } \underline{v}_2 &= (\underline{A} - (-9)\underline{I}) \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} -2 & 0 & -4 \\ -1 & 0 & -1 \\ +1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix},\end{aligned}$$

but we said \underline{v}_2 can't be $\underline{0}$. (\underline{v}_1 would also be $=\underline{0}$ here, which also can't happen)

Hence we shouldn't use the choice $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$

* for this problem.

$\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ might work in other problems.

So we have $\underline{v}_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$, $\underline{v}_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$, $\underline{v}_3 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$.

Solutions $\underline{X}_1(t) := e^{\lambda t} \underline{v}_1 = e^{-9t} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$$\begin{aligned}\underline{X}_2(t) &:= e^{\lambda t} (t \underline{v}_1 + \underline{v}_2) \\ &= e^{-9t} \left(t \begin{bmatrix} 0 \\ 0 \end{bmatrix} + \begin{bmatrix} -2 \\ 1 \end{bmatrix} \right)\end{aligned}$$

$$\begin{aligned}\underline{X}_3(t) &= e^{\lambda t} \left(\frac{t^2}{2!} \underline{v}_1 + t \underline{v}_2 + \underline{v}_3 \right) \\ &= e^{-9t} \left(\frac{t^2}{2} \begin{bmatrix} 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -2 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)\end{aligned}$$

General solution is

$$\underline{X}(t) = c_1 \underline{X}_1(t) + c_2 \underline{X}_2(t) + c_3 \underline{X}_3(t).$$

If we needed $\underline{v}_1, \underline{v}_2, \underline{v}_3, \underline{v}_4 \neq 0$ (in a different problem)
such that $(\underline{A} - \lambda I)^4 \underline{v}_4 = 0$

and chain

$$\left\{ \begin{array}{l} (\underline{A} - \lambda I) \underline{v}_4 = \underline{v}_3 \\ (\underline{A} - \lambda I) \underline{v}_3 = \underline{v}_2 \\ (\underline{A} - \lambda I) \underline{v}_2 = \underline{v}_1 \\ (\underline{A} - \lambda I) \underline{v}_1 = 0 \end{array} \right. ,$$

then we'd have everything like before,
but also add-in

$$\underline{x}_4(t) = e^{\lambda t} \left(\frac{t^3}{3!} \underline{v}_1 + \frac{t^2}{2!} \underline{v}_2 + t \underline{v}_3 + \underline{v}_4 \right)$$

However, these are lengthy and don't show up
in problems too much.